First results from two airborne campaigns over Europe in order to calibrate and validate ESA's Aeolus Wind Lidar mission

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B. Witschas, S. RahmO. Reitebuch, C. Lemmerz,U. Marksteiner, O. Lux, F. Weiler,A. Geiss (LMU), Th. Fehr (ESA)

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Knowledge for Tomorrow

Outline











Introduction

- Aeolus Cal/Val activities at DLR
- The airborne Aeolus Cal/Val payload at DLR

The WindVal III campaign, Nov/Dec 2018, Germany

- Overview
- First results and comparison to the Aeolus wind product

The AVATARE campaign, May/June 2019, Germany

Short overview

Introduction

Airborne campaigns for Aeolus validation at DLR supported by ESA (Th. Fehr)



The airborne Aeolus Cal/Val payload at DLR



A coherent [1,2,3] and a direct detection [4,5] Doppler wind lidar on-board Falcon

2-µm DWL power supply and cooling unit

> 2-µm DWL transceiver

A2D data acquisition unit, power supply and cooling unit are mounted behind (not visible)



[1] Chouza et al., 2016, ACP, [2] Weissmann et al., 2005, J-TECH, [3] Witschas et al., 2017, J-TECH
[4] Lux et al., 2018, Atmos. Meas. Technol. (2018), [5] Marksteiner et al., 2018, Remote Sensing 10.12 (2018)

The airborne Aeolus Cal/Val payload at DLR



Specifications	Demonstrator	Reference			
Parameter	DLR A2D [1,2]	DLR 2-μm DWL [3]			
Detection principle	Direct detection	Coherent detection		_	
Scanning	Fixed line-of-sight	Double-wedge scanner		-4-113	
Wavelength	354.89 nm	2022.54 nm	D-CMET		
Laser energy	50-60 mJ	1-2 mJ			
Pulse repetition rate	50 Hz	500 Hz			
Pulse length	20 ns (FWHM)	400-500 ns (FWHM)			
Telescope diameter	20 cm	10.8 cm			
Vertical resolution	300 m to 2.4 km	100 m			
Temporal averaging raw data (horizontal)	20 shots = 400 ms	single shot = 2 ms	Parameter	DLR Falcon	
Temporal averaging product (horizontal)	14 s (+4 s data gap)	1 s per LOS (500 shots), 42 s scan (21 LOS)	Max. Range Max. Altitude Max. Endurance	3700 km 12800 m 4-5 h (dep. on altitude)	
Horizontal resolution	3.6 km (18 s)	0.2 km LOS, 8.4 km scan	Take-off distance	2000 m	
Precision	1.5 m/s (Mie)	< 1 m/s	Pressurized Cabin	Yes	
(random error)	2.5 m/s (Rayleigh)		Long Range Speed	245 m/s	

[1] Lux et al., 2018, Atmos. Meas. Technol. (2018), [2] Marksteiner et al., 2018, Remote Sensing 10.12 (2018) [3] Witschas et al., 2017, Journal of Atmospheric and Oceanic Technology 34.6 (2017)

The 2-µm DWL The reference lidar

The accuracy (and the precision) of the 2-µm DWL and corresponding retrieval algorithms was verified during several campaigns within the last years by means of comparison to dropsonde measurements.

- Bias: 0.00 m/s; STD*: 1.20 m/s [1] hor. wind
- Bias: 0.08 m/s; STD*: 0.92 m/s [2] hor. wind
- Bias: 0.05 m/s, STD*: 0.20 m/s [3] vert. wind
- Bias: 0.08 m/s, STD*: 1.30 m/s [4] hor. wind

(from NAWDEX - comparison to Halo dropsondes)

* STD considers the uncertainty of dropsonde and lidar measurements

[1] Weißmann et al., 2005, Journal of Atmospheric and Oceanic Technology, Vol. 22.

- [2] Chouza et al., 2016, Atmospheric Chemistry and Physics, Vol. 16.
- [3] Witschas et al., 2017, Journal of Atmospheric and Oceanic Technology Vol. 34.
- [4] Schäfler et. al, 2018, Bulletin of the American Meteorological Society 99.8 (2018)





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The WindVal III campaign Overview





- 6 flights from Oberpfaffenhofen, Germany including a test flight and a calibration flight on 29/11/2018 (22 flight hours)
- 4 Aeolus underflights covering nearly 3000 km of the Aeolus swaths
- 1155 km long flight leg along the track from the Alps to the North Sea on 17/11



Comparison of 2-µm DWL and Aeolus Data

Procedure by an example of the first underflight on November 17





Statistical comparison 2-µm DWL measurements to ECMWF analysis



- ECMWF analysis data and 2-µm wind speed data are in good accordance (slope close to 1.0 and a bias of 0.3 m/s).
 - → ECMWF is already doing a great job (central Europe)
 - → 2-µm DWL data provides a reliable reference for Aeolus cal/val
- A few remaining outliers may arise from undetected "noise" in the 2-µm DWL data
 - \rightarrow Data filtering is currently improved

Statistical comparison

2-µm DWL measurements to Aeolus data



- Aeolus data and 2-µm data are in good accordance (slope ~ 1.00)
 → Aeolus is measuring real winds!
- The bias of about 2.5 m/s (Ray) /
 2.2 m/s (Mie) can be explained by a not-updated calibration file used for processing + instrumental drifts
 → principally solvable

The enhanced scaled median absolute deviation (MAD)
3.9 m/s (Ray) / 2.0 m/s (Mie) is explained by the low laser energy and a signal loss in the receiver (see also Wernham and Reitebuch)
may improve for second laser



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2-µm DWL wind speed measurements during AVATARE 6 Aeolus underflights performed in May/June 2019 – under analysis















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- Two airborne Aeolus Cal/Val campaigns were performed in Autumn 2018 and Spring 2019 in central Europe
- 10 successful underflights below the satellite track were performed
- The 2-µm DWL is demonstrated to be a reliable reference by means of comparison to dropsonde and ECMWF analysis data
- The first statistical comparison of Aeolus data to 2-µm DWL data looks promising
 - Rayleigh: Bias: 2.49 m/s, STD = 5.65 m/s, scaled MAD = 3.93 m/s
 - Mie : Bias: 2.24 m/s, STD = 2.68 m/s, scaled MAD = 1.99 m/s
 - The enhanced MAD for the Rayleigh winds are due to the lower laser power and signal loss in the receiver
 - The bias of Mie and Rayleigh winds is explained by a **not-updated receiver calibration** file together with **instrumental alignment drifts** that require continuous calibration (known and ongoing work)





- Finish the analysis of the recent CalVal campaigns data
- Investigate the performance of Aeolus winds for detailed scenes as for instance
 - wind quality in respective areas,
 - wind quality for respective backscatter ratios,
 - wind quality in cloudy regions,

and provide suggestions to improve the Aeolus processor

- Further refine the flight strategy for upcoming CalVal campaigns
- Install the Aeolus CalVal payload to the aircraft in August 2019 in order to head to Iceland in September 2019



